

CHAPTER 35

Engineering Metrology and Instrumentation

Slideway Cross-Section

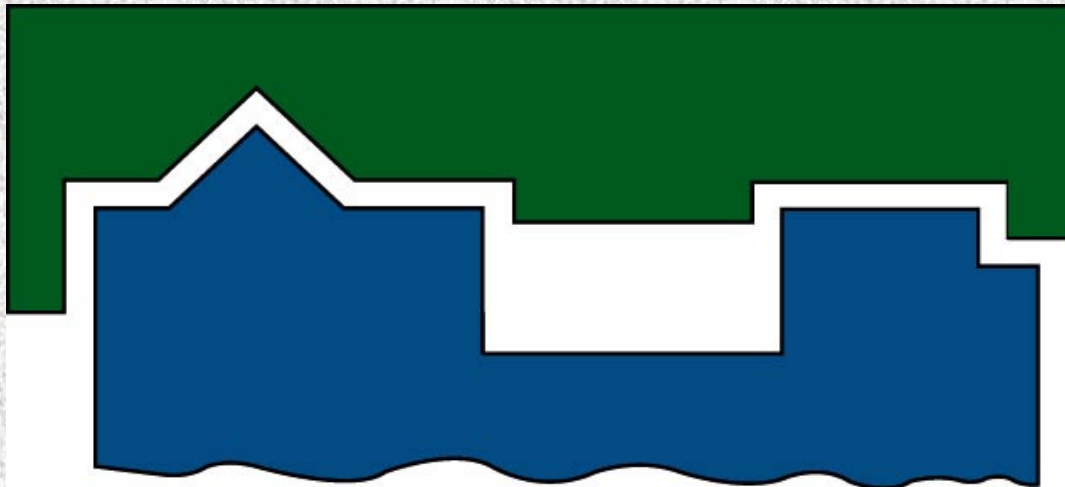


Figure 35.1 Cross-section of a machine tool slideway. The width, depth, angles, and other dimensions must be produced and measured accurately for the machine tool to function as expected.

Types of Measurement and Instruments Used

TABLE 35.1

Measurement	Instrument	Sensitivity	
		μm	$\mu\text{in.}$
Linear	Steel rule	0.5 mm	1/64 in.
	Vernier caliper	25	1000
	Micrometer, with vernier	2.5	100
	Diffraction grating	1	40
Angle	Bevel protractor, with vernier	5 min	
	Sine bar		
Comparative length	Dial indicator	1	40
	Electronic gage	0.1	4
	Gage blocks	0.05	2
Straightness	Autocollimator	2.5	100
	Transit	0.2 mm/m	0.002 in./ft
	Laser beam	2.5	100
Flatness	Interferometry	0.03	1
Roundness	Dial indicator Circular tracing	0.03	1
Profile	Radius or fillet gage		
	Dial indicator	1	40
	Optical comparator	125	5000
	Coordinate measuring machines	0.25	10
GO-NOT GO	Plug gage		
	Ring gage		
	Snap gage		
Microscopes	Toolmaker's	2.5	100
	Light section	1	40
	Scanning electron	0.001	0.04
	Laser scan	0.1	5

Caliper and Vernier

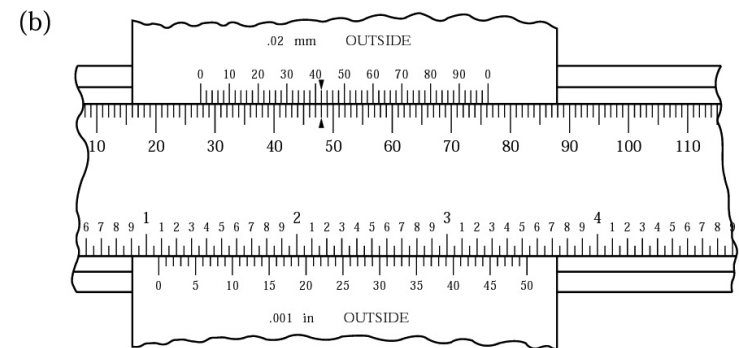
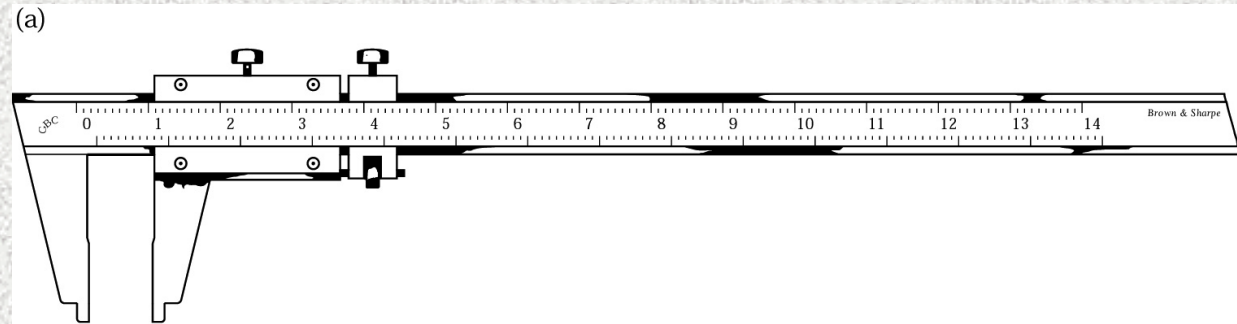


Figure 35.2 (a) A caliper gage with a vernier. (b) A vernier, reading $27.00 + 0.42 = 27.42$ mm, or $1.000 + 0.050 + 0.029 = 1.079$ in. We arrive at the last measurement as follows: First note that the two lowest scales pertain to the inch units. We next note that the 0 (zero) mark on the lower scale has passed the 1-in. mark on the upper scale. Thus, we first record a distance of 1.000 in. Next we note that the 0 mark has also passed the first (shorter) mark on the upper scale. Noting that the 1-in. distance on the upper scale is divided into 20 segments, we have passed a distance of 0.050 in. Finally note that the marks on the two scales coincide at the number 29. Each of the 50 graduations on the lower scale indicates 0.001 in., so we also have 0.029 in. Thus the total dimension is 1.000 in. + 0.050 in. + 0.029 in. = 1.079 in.

Analog and Digital Micrometers

(a)



(c)



Figure 35.3 (a) A micrometer being used to measure the diameter of round rods. *Source:* L. S. Starrett Co. (b) Vernier on the sleeve and thimble of a micrometer. Upper one reads $0.200 + 0.075 + 0.010 = 0.285$ in.; lower one reads $0.200 + 0.050 + 0.020 + 0.0003 = 0.2703$ in. These dimensions are read in a manner similar to that described in the caption for Fig. 35.2. (c) A digital micrometer with a range of 0-1 in. (0-25 mm) and a resolution of 0.00005 in. (0.001 mm). Note how much easier it is to read dimensions on this instrument than on the analog micrometer shown in (a). However, such instruments should be handled carefully. *Source:* Mitutoyo Corp.

Angle-Measuring Instruments

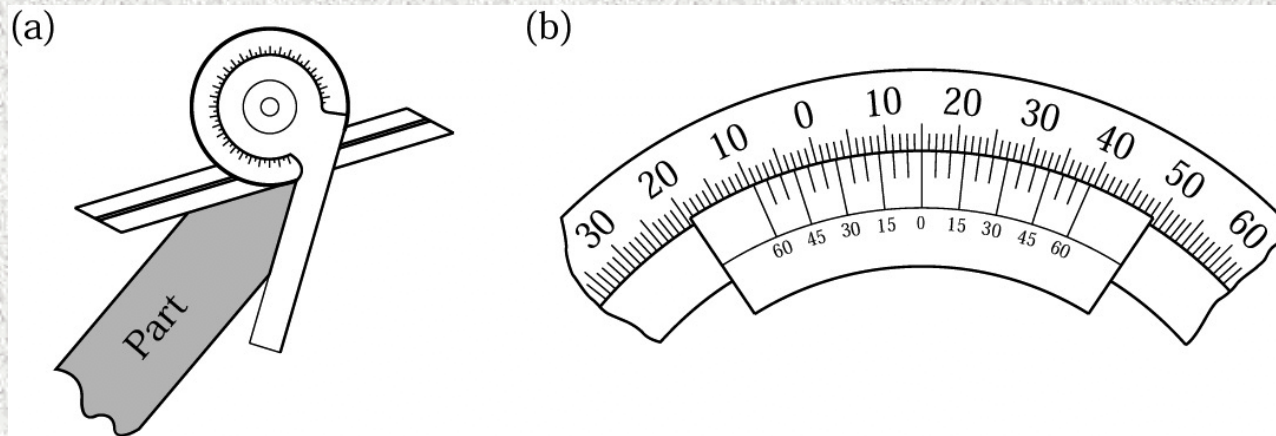
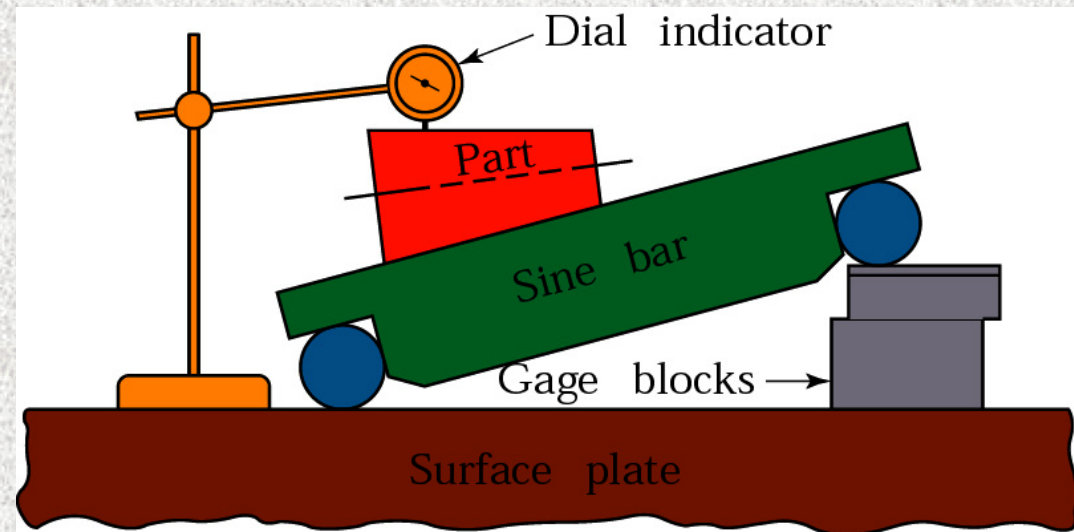


Figure 35.4 (a) Schematic illustration of a bevel protractor for measuring angles. (b) Vernier for angular measurement, indicating $14^{\circ} 30'$.

Figure 35.5 Setup showing the use of a sine bar for precision measurement of workpiece angles.



Dial Indicators

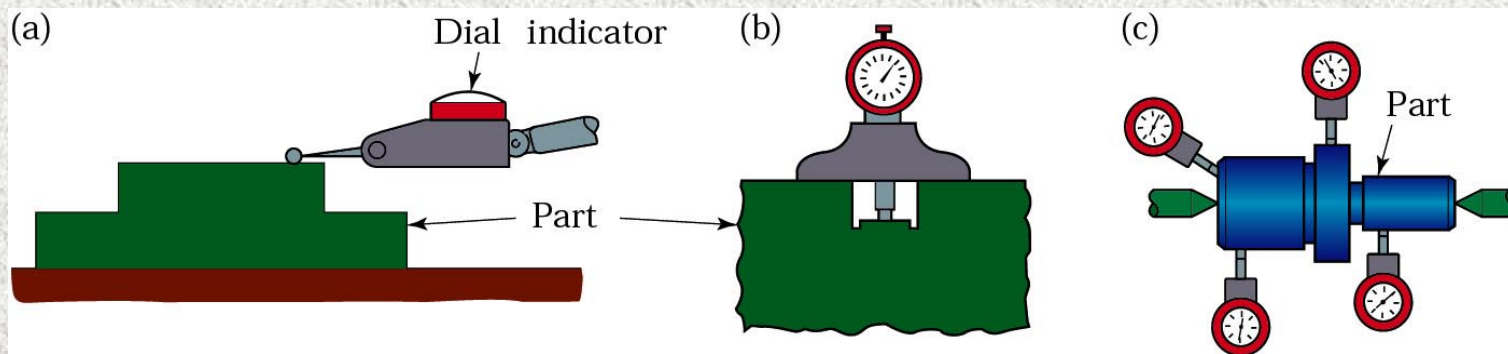


Figure 35.5 Setup showing the use of a sine bar for precision measurement of workpiece angles.

Electronic Gages



Figure 35.7 An electronic gage for measuring bore diameters. The measuring head is equipped with three carbide-tipped steel pins for wear resistance. The LED display reads 29.158 mm. *Courtesy of TESA SA.*

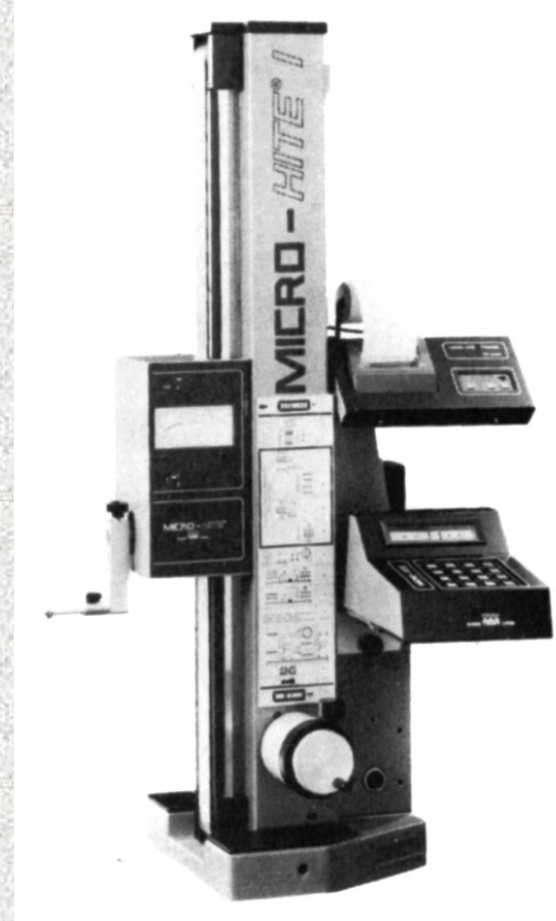


Figure 35.8 An electronic vertical length measuring instrument, with a sensitivity of $1\ \mu\text{m}$ ($40\ \mu\text{in.}$). *Courtesy of TESA SA.*

Laser Scan Micrometer and Straightness Measurement

Figure 35.9 Two types of measurement made with a laser scan micrometer. *Source: Mitutoyo Corp.*

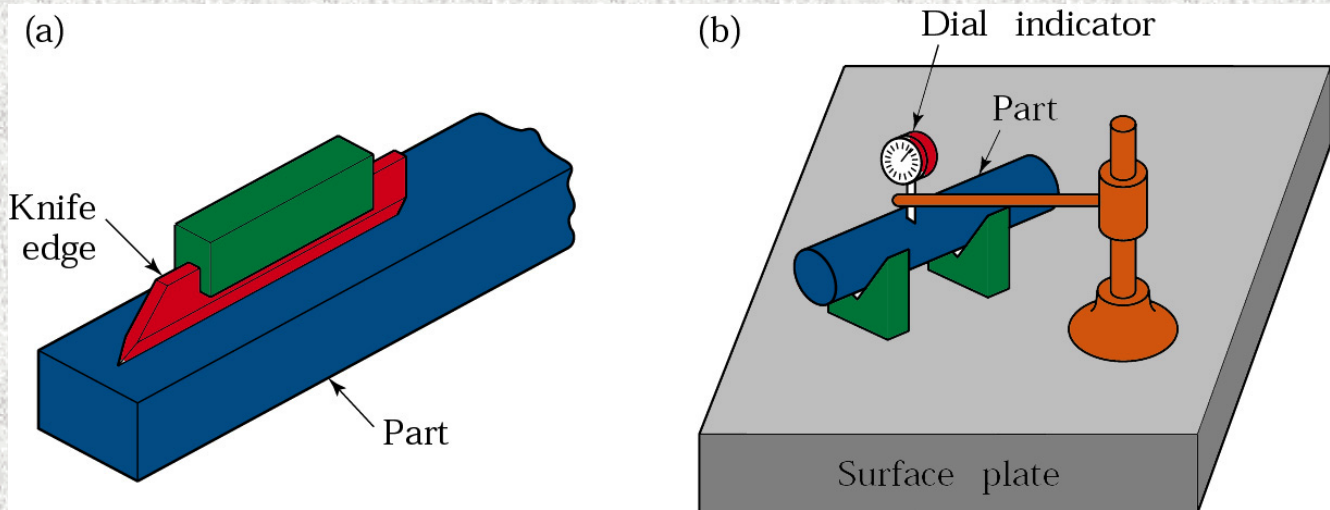
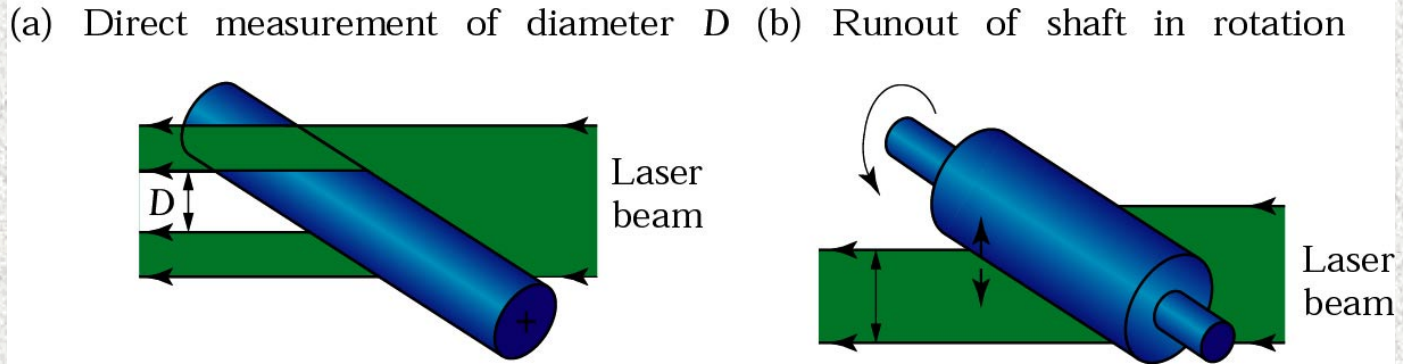


Figure 35.10 Measuring straightness with (a) a knife-edge rule and (b) a dial indicator attached to a movable stand resting on a surface plate. *Source: F. T. Farago.*

Interferometry

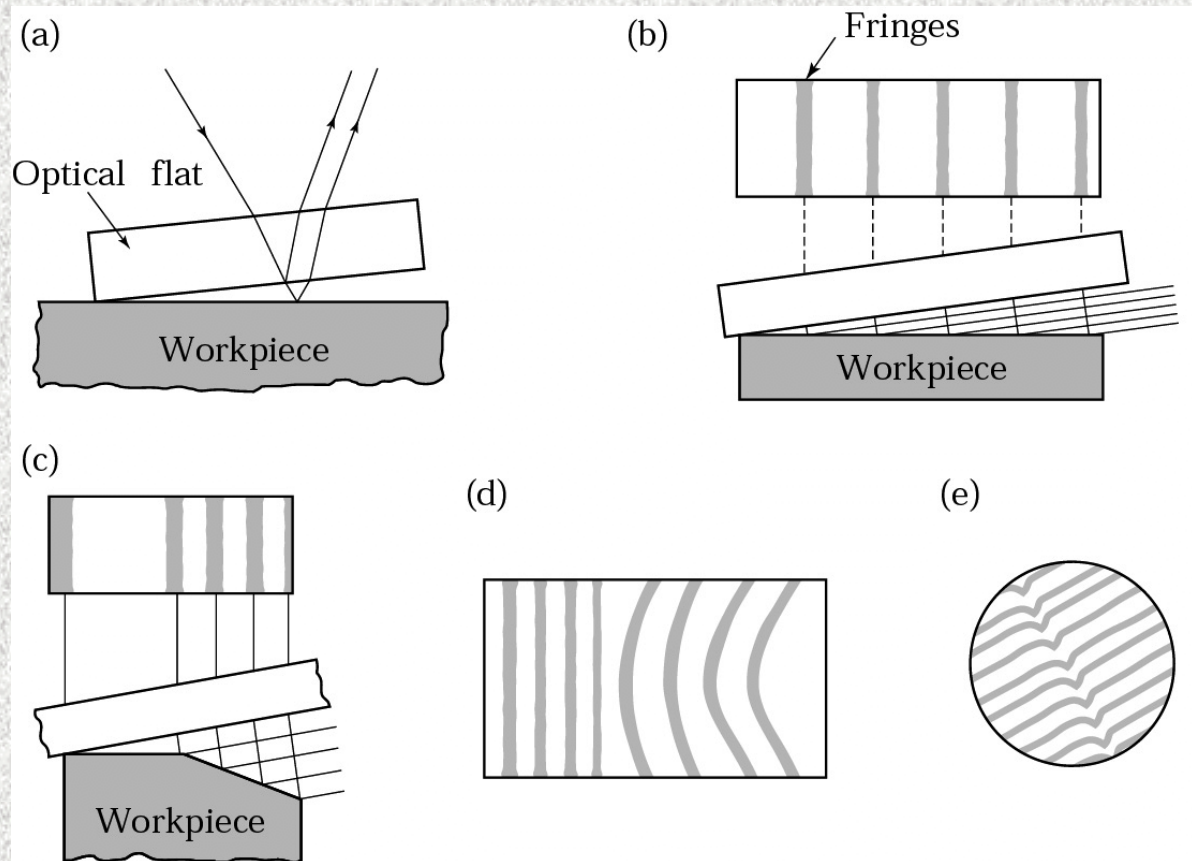
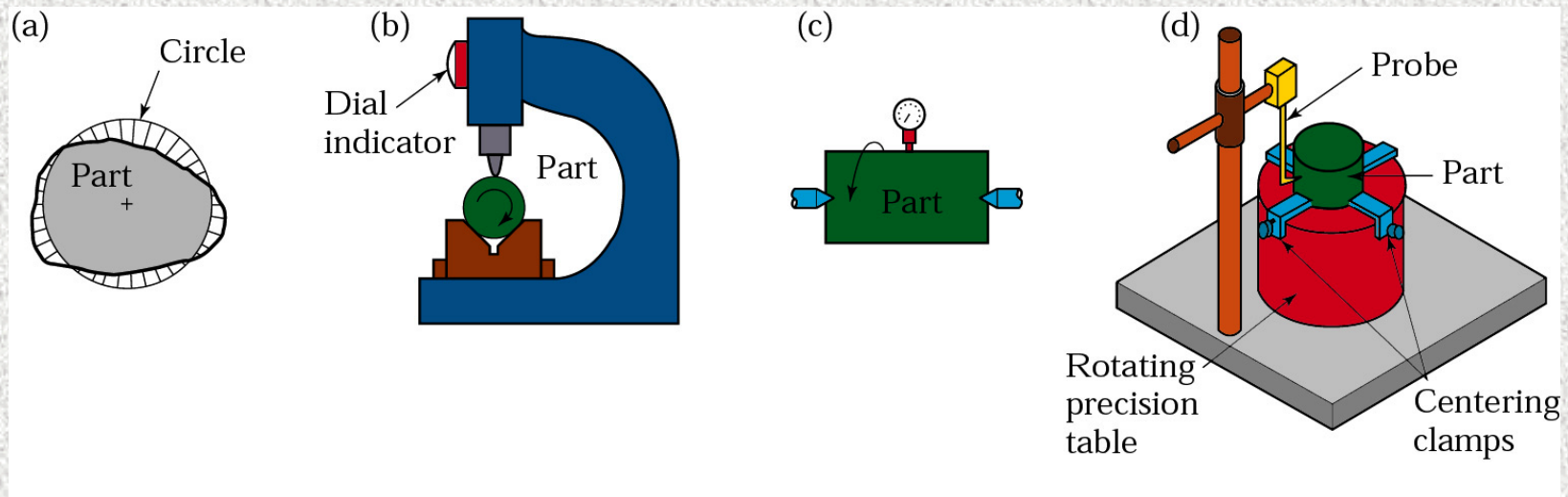


Figure 35.11 (a) Interferometry method for measuring flatness using an optical flat. (b) Fringes on a flat inclined surface. An optical flat resting on a perfectly flat workpiece surface will not split the light beam, and no fringes will be present. (c) Fringes on a surface with two inclinations. *Note:* the greater the incline, the closer the fringes. (d) Curved fringe patterns indicate curvatures on the workpiece surface. (e) Fringe pattern indicating a scratch on the surface.

Measuring Roundness

Figure 35.12 (a) Schematic illustration of “out of roundness” (exaggerated). Measuring roundness using (b) V-block and dial indicator, (c) part supported on centers and rotated, and (d) circular tracing, with part being rotated on a vertical axis. *Source: After F. T. Farago.*



Measuring Profiles

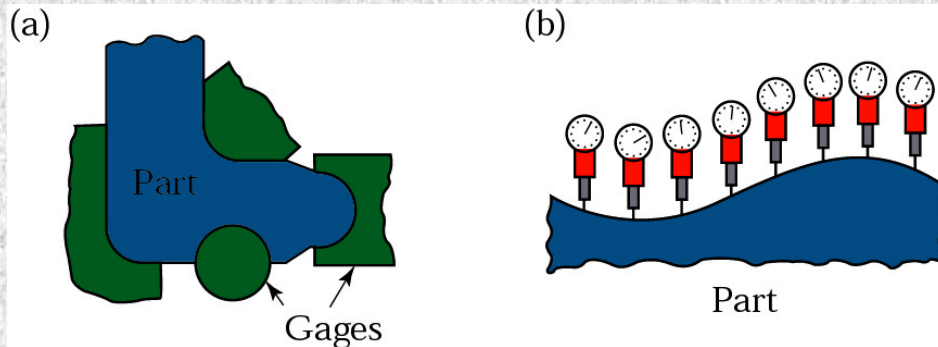


Figure 35.13 Measuring profiles with (a) radius gages and (b) dial indicators.

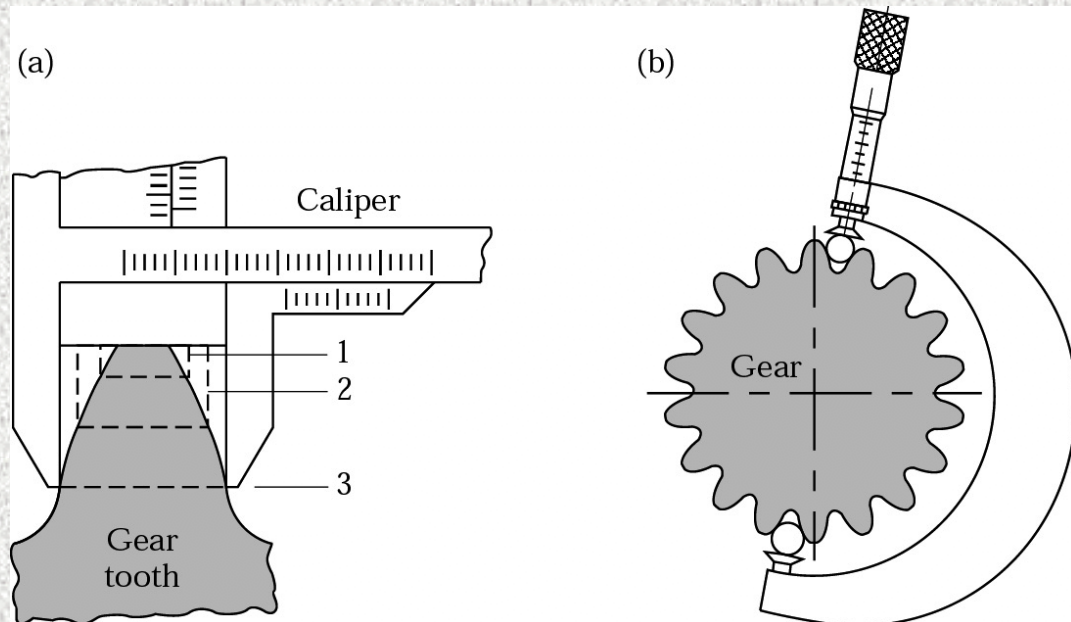


Figure 35.13 Measuring profiles with (a) radius gages and (b) dial indicators.

Horizontal-Beam Contour Projector

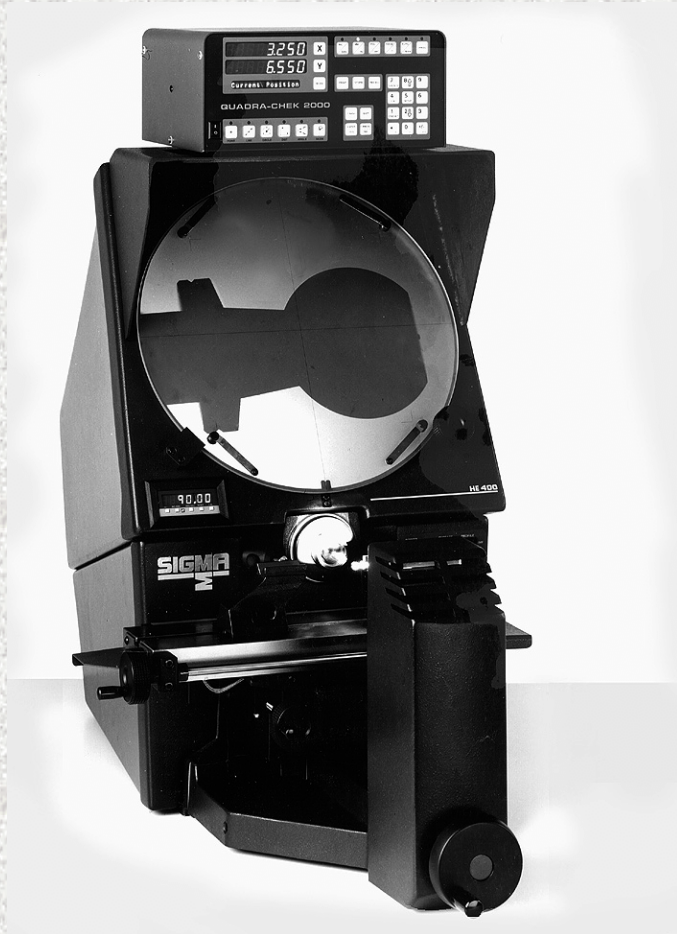


Figure 35.15 A bench model horizontal-beam contour projector with a 16 in.-diameter screen with 150-W tungsten halogen illumination. *Courtesy of L. S. Starrett Company, Precision Optical Division.*

Coordinate Measuring Machine

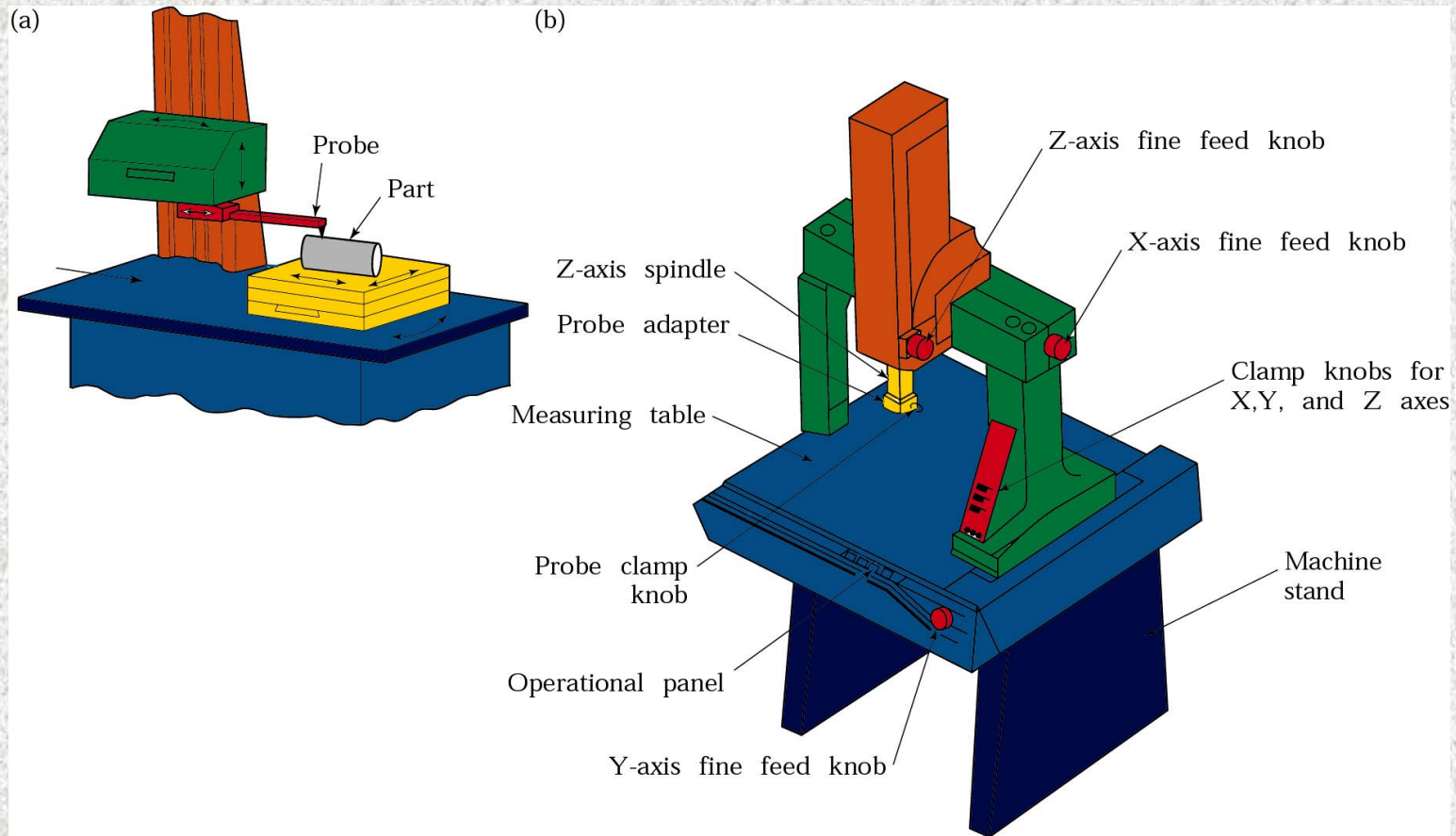
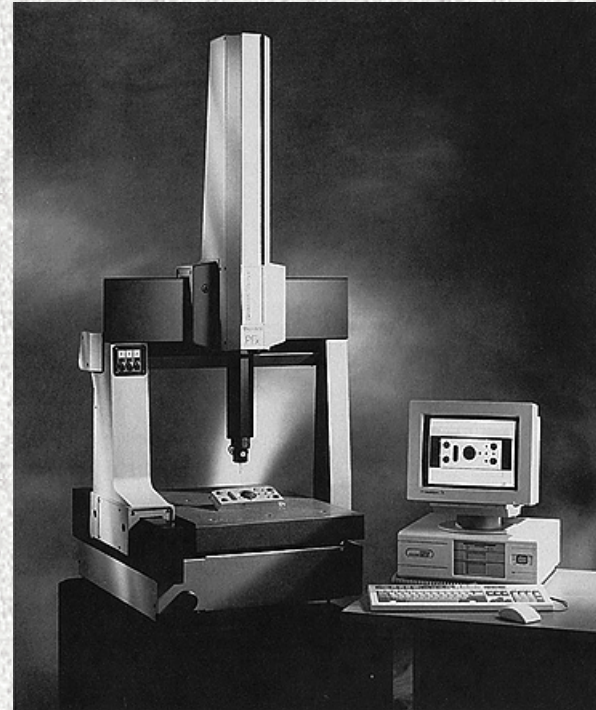


Figure 35.16 (a) Schematic illustration of one type of coordinate measuring machine. (b) Components of another type of coordinate measuring machine. These machines are available in various sizes and levels of automation and with a variety of probes (attached to the probe adapter), and are capable of measuring several features of a part. *Source:* Mitutoyo Corp.

Coordinate Measuring Machine

Figure 35.17 A coordinate measuring machine. Brown & Sharpe Manufacturing.



Gages

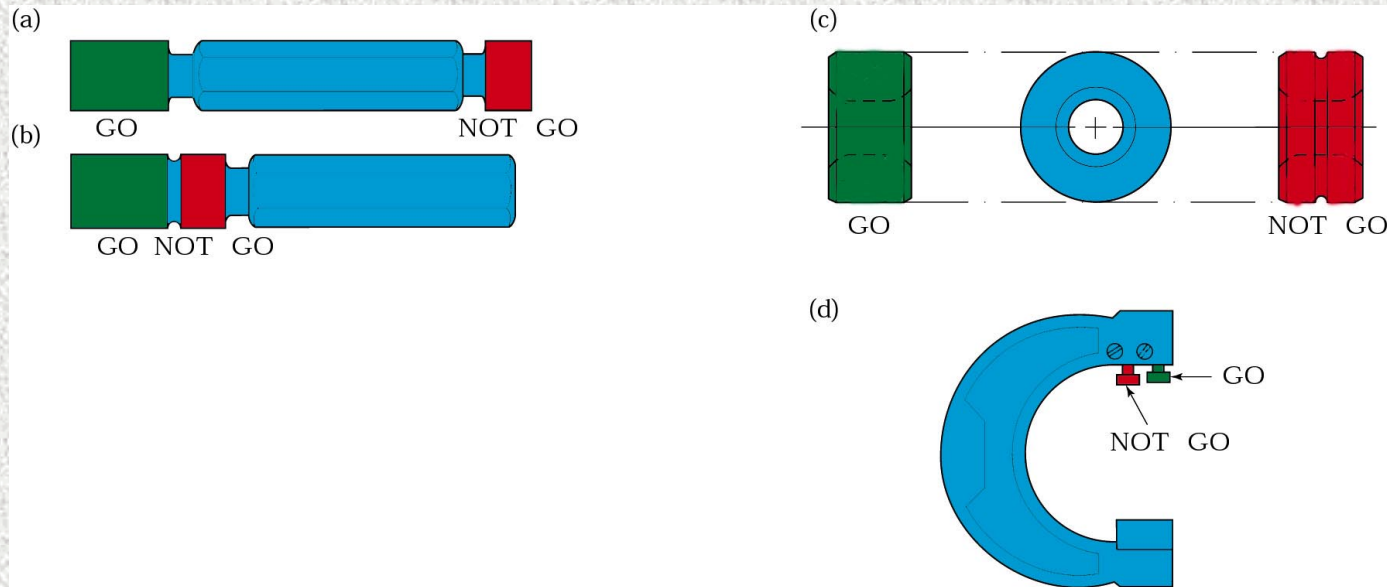


Figure 35.18 (a) Plug gage for holes, with GO-NOT GO on opposite ends. (b) Plug gage with GO-NOT GO on one end. (c) Plain ring gages for gaging round rods. Note the difference in knurled surfaces to identify the two gages. (d) Snap gage with adjustable anvils.

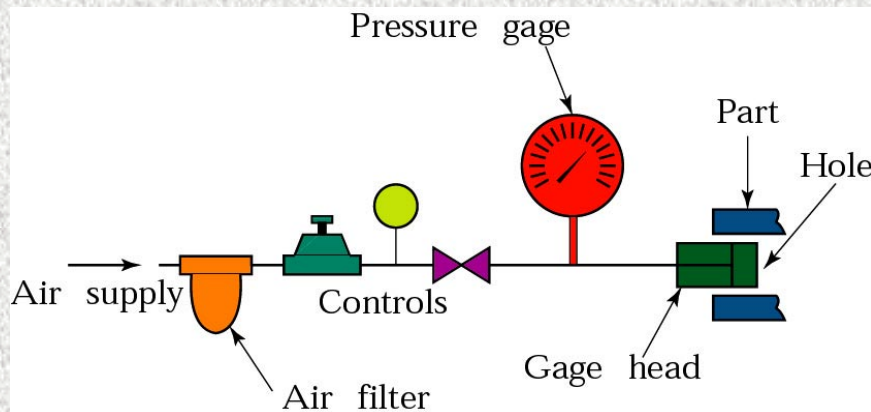


Figure 35.19 Schematic illustration of one type of pneumatic gage.

Tolerance Control

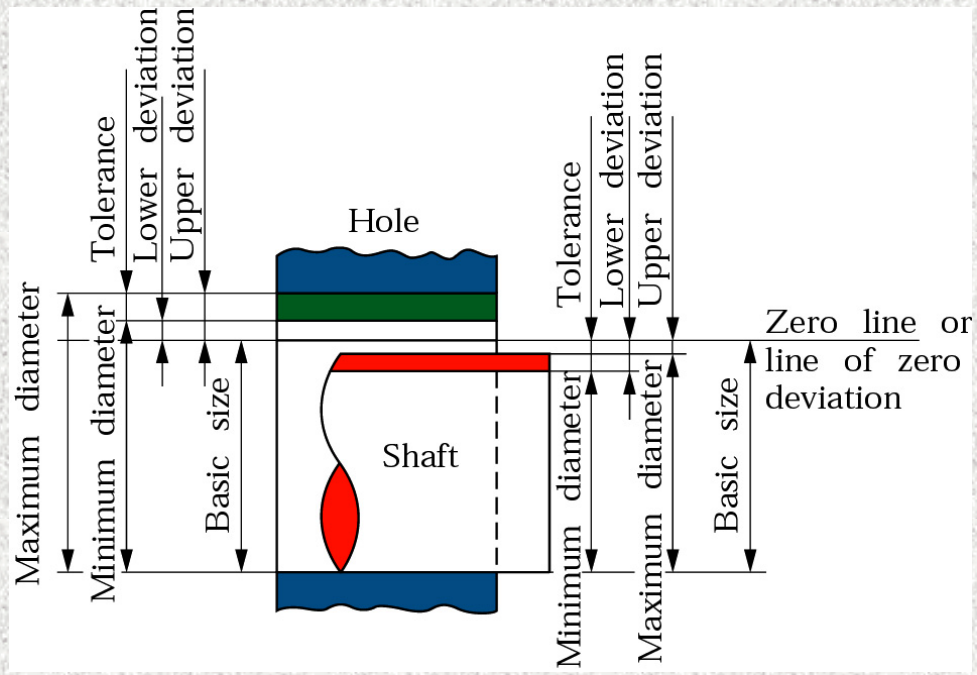


Figure 35.20 Basic size, deviation, and tolerance on a shaft, according to the ISO system.

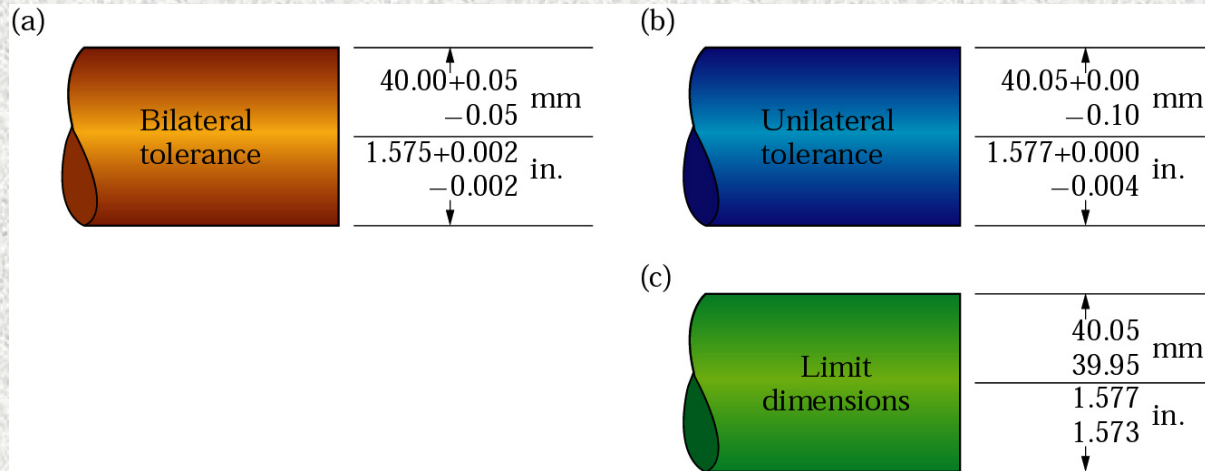


Figure 35.21 Various methods of assigning tolerances on a shaft. Source: L. E. Doyle.

Tolerances as a Function of Size

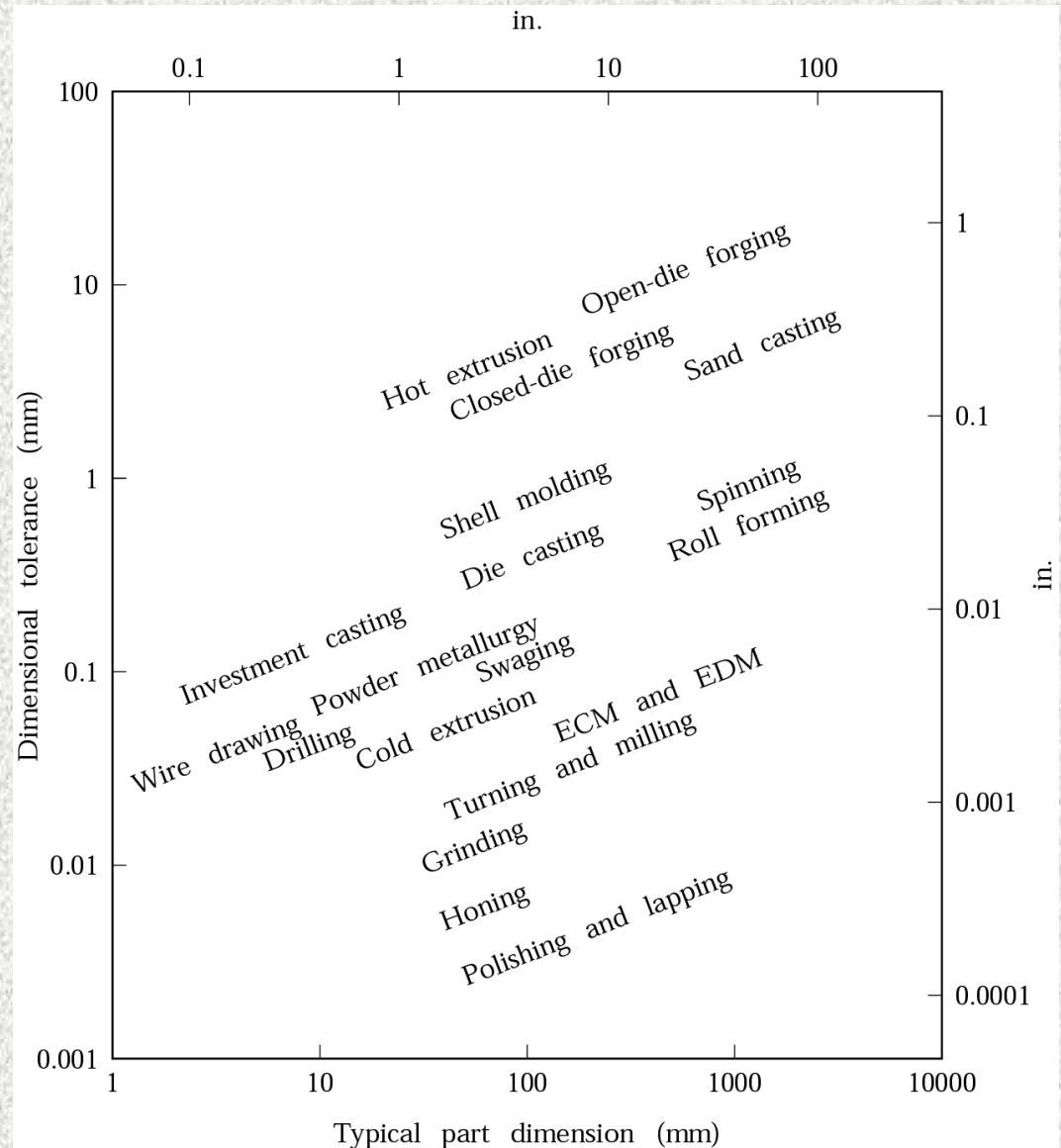
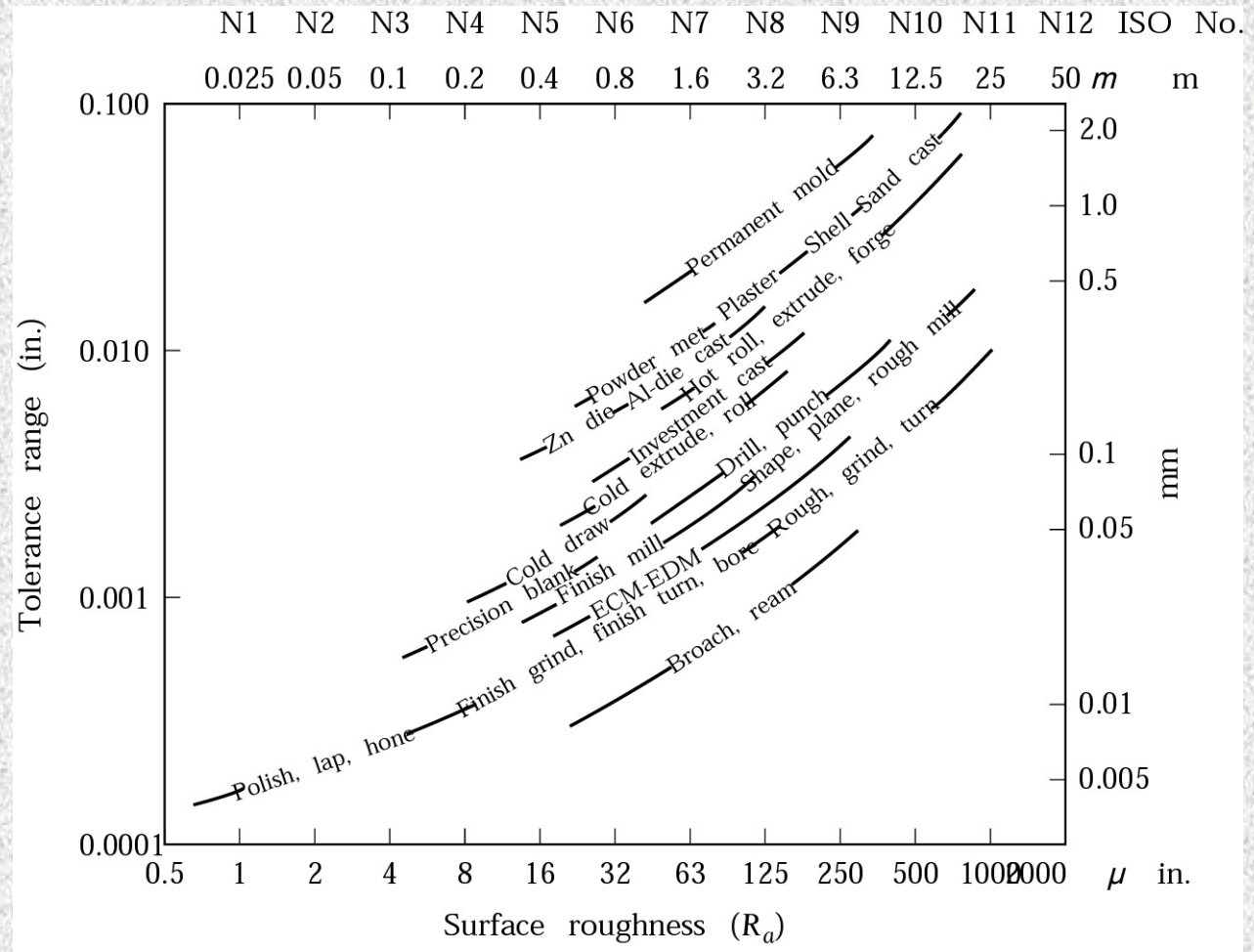


Figure 35.22 Tolerances as a function of part size for various manufacturing processes. *Note:* Because many factors are involved, there is a broad range for tolerances.

Tolerances and Surface Roughnesses

Figure 35.23 Tolerances and surface roughness obtained in various manufacturing processes. These tolerances apply to a 25-mm (1-in.) workpiece dimension. *Source: J. A. Schey.*



Engineering Symbols

Figure 35.24 Geometric characteristic symbols to be indicated on engineering drawings of parts to be manufactured. *Source:* The American Society of Mechanical Engineers.

(a)

Type of feature	Type of tolerance	Characteristic	Symbol
Individual (no datum reference)	Form	Flatness	
		Straightness	
		Circularity (roundness)	
		Cylindricity	
Individual or related	Profile	Profile of a line	
		Profile of a surface	
Related (datum reference required)	Orientation	Perpendicularity	
		Angularity	
		Parallelism	
	Location	Position	
		Concentricity	
	Runout	Circular runout	
Total runout			

(b)

$\boxed{.605}$

Basic, or exact, dimension

$\boxed{-A-}$

Datum feature symbol

\textcircled{M}

Maximum material condition

\textcircled{S}

Regardless of feature size

\textcircled{L}

Least material condition

\textcircled{P}

Projected tolerance zone

\emptyset

Diametrical (cylindrical) tolerance zone or feature

$\textcircled{\oplus} \textcircled{\emptyset} .005 \textcircled{M} \textcircled{A}$

Feature control frame

$\textcircled{A1}$

Datum target symbol